

# Doehler & Haass

# Locomotive decoder Vehicle function decoder

# Locomotive decoder

Vehicle function decoder

DH05C	PD05A
DH10C	PD06A
DH12A	PD12A
DH14B	PD18A
DH16A	PD21A
DH18A	
DH21A/B	
DH22A/B	

FH05B FH16A FH18A FH22A

SX1

SX2

DCC

MM

AC ~ DC =







Ne 18

PluX 12/16/22

SUSI

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#### 1 Introduction

The locomotive decoders supports various data formats and operating modes:

Decoder	SX1, SX2	DCC	MM1, MM2	DC-analog	AC-analog
DH05C, DH10C, DH12A, DH14B, DH16A, DH18A	X	Х	X	X	
DH21A/B, DH22A/B	X	X	X	X	X
FH05B, FH16A, FH18A	X	X	X	X	
FH22A	X	X	X	X	X
PD05A	X	Х			
PD06A	X	Х		X	
PD12A, PD18A, PD21A		Х		X	

Our decoders can be used for normal direct current motors as well for coreless motors.

The operation on alternating current supplied layouts with switching impulse is not allowed! The switching impulse destroys the decoder (exception: DH21A/B, DH22A/B and FH22A)!

The operation of inductive consumers (decouplers, relays, etc.) requires the connection of freewheeling diodes (see supplement 4).

# 2 Safety instructions

This product is not suitable for children under 14 years.

It might be swallowed by children under 3 years!

An improper use involves a risk of injury due to sharp edges and points.

# 3 Warranty

The functioning of every decoder is fully tested before delivery. Should nevertheless a failure occur, please contact the dealer where you purchased the decoder or directly the producer (Doehler & Haass). The warranty period is two years from the data of purchase.

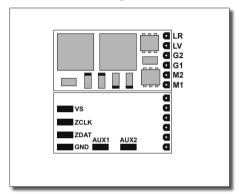
# 4 Support and help

In case you have any problems or questions please contact us by email: **technik@doehler-haass.de** Usually you will get an answer within a few days.



#### 5 Locomotive decoder

#### DH05C 1st generation



Specifications	DH05C
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 With SUSI interface (if AUX3/AUX4 deactivated)	13,2 x 6,8 x 1,4 0,5 A 0,5 A <b>18 V</b> each 150 mA each 300 mA unamplified *) X
Connecting options Without connection wires With ribbon cable for interface per NEM651 With connection wires	DH05C-0 DH05C-1 DH05C-3

G1, G2 ..... Track connection 1, 2

LV, LR .....Front light, rear light (each 150 mA)

AUX1, AUX2.....Additional function 1, 2 (each 300 mA)

**VS**.....Supply voltage (also for SUSI)

ZCLK.....SUSI clock (or AUX3 unamplified) \*)

ZDAT ......SUSI data (or AUX4 unamplified) \*)

**GND** ...... Ground (0 V)

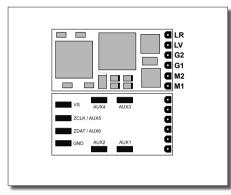
If necessary: Connect blue wire (common return conductor) to VS.

You can connect a buffer capacitor to VS (+) and GND (-).

\*) Unamplified function outputs: See supplement 3.



## DH05C (2<sup>nd</sup> generation)



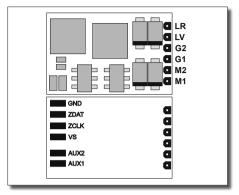
Specifications	DH05C
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4, AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated)	after publication 0,5 A 0,5 A 30 V each 150 mA each 300 mA unamplified *)
Connecting options Without connection wires With connection wires	DH05C-0 DH05C-3

\*) Unamplified function outputs: See supplement 3.

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to VS (+) and GND (-).



### DH10C (1st generation)



Specifications	DH10C
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 With SUSI interface (if AUX3/AUX4 deactivated)	14,2 x 9,3 x 1,5 1,0 A 1,0 A 30 V each 150 mA each 300 mA unamplified *)
Connecting options Without connection wires With ribbon cable for interface per NEM651 With connection wires	DH10C-0 DH10C-1 DH10C-3

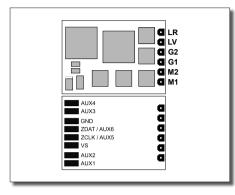
\*) Unamplified function outputs: See supplement 3.

If necessary: Connect blue wire (common return conductor) to VS.

You can connect a buffer capacitor to VS (+) and GND (-).



#### DH10C (2<sup>nd</sup> generation)



	Specifications	DH10C
	Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 Function outputs: AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated)	12,7 x 8,9 x 1,4 1,5 A 1,5 A 30 V each 150 mA each 300 mA each 1,0 A unamplified *)
2	Connecting options Without connection wires With ribbon cable for interface per NEM651 With connection cable for interface per NEM651 With connection wires 6 pin connector for direct plugging (NEM651)	DH10C-0 DH10C-1 DH10C-2 DH10C-3 DH10C-4

\*) Unamplified function outputs: See supplement 3.

M1, W2	Motor connection 1, 2
G1, G2	Track connection 1, 2

LV, LR ..... Front light, rear light (each 150 mA)

AUX1, AUX2..... Additional function 1, 2 (each 300 mA)

AUX3, AUX4..... Unamplified function 3, 4 (each 1,0 A)

VS..... Supply voltage (also for SUSI)

ZCLK/AUX5 ..... SUSI clock (or AUX5 unamplified) \*)

**ZDAT/AUX6**...... SUSI data (or AUX6 unamplified) \*)

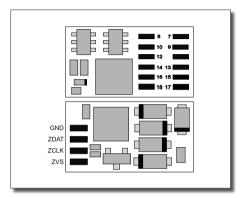
**GND** ...... Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS.

You can connect a buffer capacitor to VS (+) and GND (-).



#### DH<sub>12</sub>A



Specifications	DH12A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4, AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated)	14,5 x 8,0 x 3,0 1,5 A 1,5 A 30 V each 150 mA each 300 mA unamplified *)
Connecting options 12 pin connector for direct plugging (PluX12)	DH12A

\*) Unamplified function outputs: See supplement 3.

VS.....Supply voltage

**ZVS** .....SUSI supply voltage

ZCLK.....SUSI clock (or AUX5 unamplified) \*)

**ZDAT** ......SUSI data (or AUX6 unamplified) \*)

**GND** ...... Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).

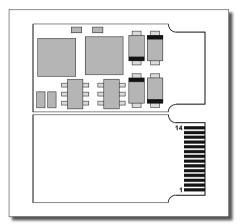
#### PluX12 interface

	1	2	
	3	4	
	5	6	
LV	7	8	M1
VS	9	10	M2
Index	11	12	G1
LR	13	14	G2
) AUX3	15	16	AUX1
) AUX4	17	18	AUX2
	19	20	
	21	22	

# D&H

# **Locomotive/Vehicle function decoder** from firmware version 3.12

#### DH14B



Specifications	DH14B
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 With SUSI interface (if AUX3/AUX4 deactivated)	18,5 x 9,2 x 1,7 1,0 A 1,0 A 30 V each 150 mA each 300 mA unamplified *) X
Connecting option 14 pole foil plug for direct plugging (mTc14)	DH14B

\*) Unamplified function outputs: See supplement 3.

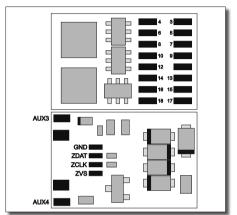
#### mTc14 interface

<u></u>	2	ო	4	വ	9	7	ω	o	10	1	12	13	14
G2	G2	$\geq$	AUX2	ZDAT	GND	M2	<u>Z</u>	GND	ZCLK	AUX1	LR	G1	G1

There is no connection possibility (VS) for the common return conductor (blue wire) or a buffer capacitor.



# DH16A (1st generation)



Specifications	DH16A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 Function outputs: AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated	16,7 x 10,9 x 2,8 1,5 A 1,5 A 30 V each 150 mA each 300 mA each 1,0 A unamplified *)
Connecting options Without connection wires With connection cable for interface per NEM652 With connection wires 16 pin connector for direct plugging (PluX16)	DH16A-0 DH16A-2 DH16A-3 DH16A-4

**M1, M2**..... Motor connection 1, 2

**G1, G2**.....Track connection 1, 2

LV, LR ..... Front light, rear light (each 150 mA)

AUX1, AUX2..... Additional function 1, 2 (each 300 mA)

AUX3, AUX4..... Additional function 3, 4 (each 1.0 A)

VS.....Supply voltage

**ZVS** ......SUSI supply voltage

ZCLK.....SUSI clock (or AUX5 unamplified) \*)

**ZDAT** ......SUSI data (or AUX6 unamplified) \*)

**GND** ...... Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).

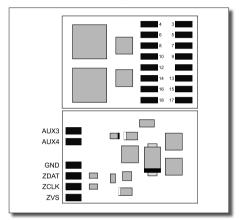
CCLK GND LV VS ndex LR

ZDAT
ZVS
M1
M2
M2
G1
G2
AUX1

# \*) Unamplified function outputs: See supplement 3. PluX16 interface



#### DH16A (2<sup>nd</sup> generation)



Specifications	DH16A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 Function outputs: AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated	after publication 1,5 A 1,5 A 30 V each 150 mA each 300 mA each 1,0 A unamplified *)
Connecting options Without connection wires With connection cable for interface per NEM652 With connection wires 16 pin connector for direct plugging (PluX16)	DH16A-0 DH16A-2 DH16A-3 DH16A-4

M1, M2	Motor	connection	1,	2

G1, G2.....Track connection 1, 2

LV, LR .....Front light, rear light (each 150 mA)

AUX1, AUX2.....Additional function 1, 2 (each 300 mA)

AUX3, AUX4..... Additional function 3, 4 (each 1,0 A)

VS.....Supply voltage

**ZVS** ......SUSI supply voltage

**ZCLK**.....SUSI clock (or AUX5 unamplified) \*)

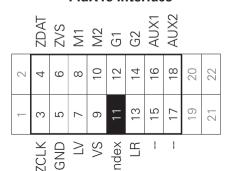
**ZDAT** ......SUSI data (or AUX6 unamplified) \*)

**GND** ...... Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).

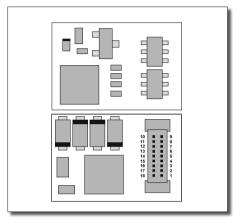
#### \*) Unamplified function outputs: See supplement 3.

#### PluX16 interface





# DH18A (1st generation)



Specifications	DH18A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4, AUX5, AUX6 With SUSI interface (if AUX3/AUX4 deactivated)	13,5 x 9,0 x 2,8 1,0 A 1,0 A 30 V each 150 mA each 300 mA unamplified *)
Connecting option 18 pin connector for direct plugging (Next18)	DH18A

\*) Unamplified function outputs: See supplement 3.

#### **Next18 interface**

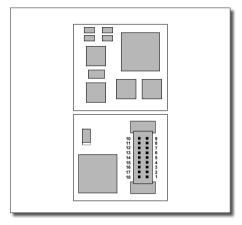
G1	LR	AUX5 *)	NS	GND	ZDAT	AUX2	M2	<b>G</b> 2
18	17	16	15	14	13	12	11	10
_	2	3	4	2	9	7	œ	6
	Σ	AUX1	ZCLK	GND	S	) AUX6	$\geq$	G2

M1, M2	Motor connection 1, 2
G1, G2	Track connection 1, 2
LV, LR	Front light, rear light (each 150 mA)
AUX1, AUX2	Additional function 1, 2 (each 300 mA)
AUX5, AUX6	Unamplified function 5, 6 *)
VS	Supply voltage (also for SUSI)
ZCLK	SUSI clock (or AUX3 unamplified) *)
<b>ZDAT</b>	SUSI data (or AUX4 unamplified) *)
GND	Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to VS (+) and GND (-).



## DH18A (2<sup>nd</sup> generation)



Specifications	DH18A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4, AUX5, AUX6 With SUSI interface (if AUX3/AUX4 deactivated)	9,7 x 8,9 x 2,8 1,5 A 1,5 A 30 V each 150 mA each 300 mA unamplified *)
Connecting option 18 pin connector for direct plugging (Next18)	DH18A

\*) Unamplified function outputs: See supplement 3.

#### **Next18 interface**

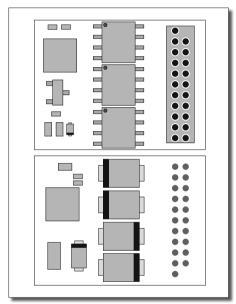
G1	LR	AUX5 *)	ΛS	GND	ZDAT	AUX2	M2	G2
18	17	16	15	14	13	12	11	10
_	2	လ	4	2	9	7	œ	6
<u>G</u> 1	Σ	AUX1	ZCLK	GND	ΛS	9XNY	$\geq$	G2

M1, M2	Motor connection 1, 2
G1, G2	Track connection 1, 2
LV, LR	Front light, rear light (each 150 mA)
AUX1, AUX2	Additional function 1, 2 (each 300 mA)
AUX5, AUX6	Unamplified function 5, 6 *)
VS	Supply voltage (also for SUSI)
ZCLK	SUSI clock (or AUX3 unamplified) *)
ZDAT	SUSI data (or AUX4 unamplified) *)
GND	Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to VS (+) and GND (-).



# DH21A (1st generation)



Specifications	DH21A-4
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Switching voltage at AC analog: Max. 45 V peak = 30 V eff. Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 Function outputs: AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated)	20,7 x 15,8 x 5,2 2,0 A 2,0 A 30 V X each 150 mA each 300 mA each 1,0 A unamplified *)
Connecting option 21 pin socket board for direct plugging (Märklin/TRIX mtc21)	DH21A-4

<sup>\*)</sup> Unamplified function outputs: See supplement 3.



### DH21A (1st generation)

#### 21 pin interface

	1	22	G1
	2	21	G2
	3	20	GND
AUX4	4	19	M1
ZCLK	5	18	M2
ZDAT	6	17	
LR	7	16	VS
LV	8	15	AUX1
	9	14	AUX2
	10	13	AUX3
Index	11	12	VCC
			•

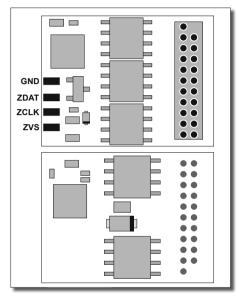
M1, M2 ∨	lotor connection 1, 2
<b>G1, G2</b> Tr	ack connection 1, 2
<b>LV, LR</b> Fr	ront light, rear light (each 150 mA)
<b>AUX1, AUX2</b> A	dditional function 1, 2 (each 300 mA)
<b>AUX3, AUX4</b> A	dditional function 3, 4
<b>VS</b>	upply voltage (also for SUSI)
<b>ZCLK</b>	USI clock (or AUX5 unamplified) *)
<b>ZDAT</b> S	USI data (or AUX6 unamplified) *)
<b>GND</b> G	round (0 V)
VCC+	5 V / max. 15 mA

<sup>\*)</sup> Unamplified function outputs: See supplement 3.

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to VS (+) and GND (-).



# DH21A (2<sup>nd</sup> generation)



Specifications	DH21A-0/2/3/4	DH21A-5
Dimensions [mm]	20,7 x 15,8 x 5,2	20,7 x 15,8 x 5,2
Total load	2,0 A	2,0 A
Maximum motor current	2,0 A	2,0 A
Maximum operating voltage	30 V	30 V
Switching voltage at AC analog:	X	X
Max. 45 V peak = 30 V eff.		
Function outputs for light:	each 150 mA	each 150 mA
LV, LR (dimmable)		
Function outputs:	each 300 mA	each 300 mA
AUX1, AUX2 (dimmable)		
Function outputs: AUX3, AUX4	each 1,0 A	unamplified *)
Function outputs: AUX5, AUX6	unamplified *)	unamplified *)
With SUSI interface	X	X
(if AUX5/AUX6 deactivated)		
Connecting options		
Without connection wire	DH21A-0	
With connection cable for	DH21A-2	
interface per NEM652		
With connection wires	DH21A-3	
21 pin socket board for direct plugging	DH21A-4	
(Märklin/TRIX mtc21)		
21 pin socket board for direct plugging		DH21A-5
(NEM660/RCN-121)		

<sup>\*)</sup> Unamplified function outputs: See supplement 3.



#### DH21A (2<sup>nd</sup> generation)

GPIO	1	22	G1
_	2	21	G2
	3	20	GND
AUX4	4	19	M1
ZCLK	5	18	M2
ZDAT	6	17	
LR	7	16	VS
LV	8	15	AUX1
	9	14	AUX2
	10	13	AUX3
Index	11	12	VCC

M1, M2 Motor connection 1, 2
<b>G1, G2</b> Track connection 1, 2
LV, LR Front light, rear light (each 150 mA)
AUX1, AUX2 Additional function 1, 2 (each 300 mA)
AUX3, AUX4 Additional function 3, 4 †)
VSSupply voltage
<b>ZVS</b> SUSI supply voltage
<b>ZCLK</b> SUSI clock (or AUX5 unamplified) *)
<b>ZDAT</b> SUSI data (or AUX6 unamplified) *)
<b>GND</b> Ground (0 V)
GPIO General input / output (max. +5 V / max. 3 mA)
<b>VCC</b> +5 V / max. 15 mA

<sup>\*)</sup> Unamplified function outputs: See supplement 3.

<sup>†</sup>) The DH21A existists in two different hardware variants:

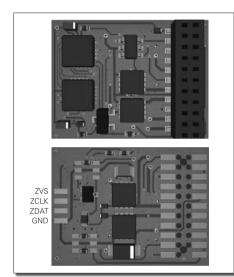
- Function outputs AUX3, AUX4: each 1,0 A (connecting option -0/-2/-3/-4)

- Function outputs AUX3, AUX4: unamplified \*) (connecting option -5)

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).



# DH21B-4



Specifications	DH21B-4
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Switching voltage at AC analog: Max. 45 V peak = 30 V eff. Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 Function outputs: AUX5, AUX6 Function outputs: AUX7, AUX8 With SUSI interface	20,7 x 15,8 x 5,2 2,0 A 2,0 A 30 V X each 150 mA each 300 mA each 1,0 A unamplified *) unamplified *)
Connecting option 21 pin socket board for direct plugging (Märklin/TRIX mtc21)	DH21B-4

\*) Unamplified function outputs: See supplement 3.



#### DH21B-4

21	pin	interface
----	-----	-----------

GPIO	1	22	G1
*) AUX7	2	21	G2
*) AUX6	3	20	GND
AUX4	4	19	M1
ZCLK	5	18	M2
ZDAT	6	17	AUX5 *
LR	7	16	VS
LV	8	15	AUX1
	9	14	AUX2
	10	13	AUX3
Index	11	12	VCC

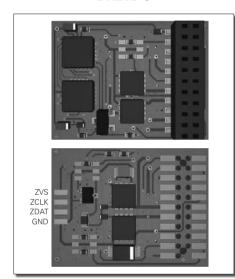
M1, M2 Motor connection 1, 2
<b>G1, G2</b> Track connection 1, 2
LV, LR Front light, rear light (each 150 mA)
AUX1, AUX2 Additional function 1, 2 (each 300 mA)
AUX3, AUX4 Additional function 3, 4 (each 1,0 A)
AUX5 AUX7 Unamplified function *)
VSSupply voltage
<b>ZVS</b> SUSI supply voltage
ZCLKSUSI clock
ZDAT SUSI data
<b>GND</b> Ground (0 V)
<b>GPIO</b> General input / output (max. +5 V / max. 3 mA)
or AUX8 unamplified *)
<b>VCC</b> +5 V / max. 15 mA

<sup>\*)</sup> Unamplified function outputs: See supplement 3.

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).



# DH21B-5



Specifications	DH21B-5
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Switching voltage at AC analog: Max. 45 V peak = 30 V eff.	20,7 x 15,8 x 5,2 2,0 A 2,0 A 30 V X
Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 Function outputs: AUX5, AUX6 Function outputs: AUX7, AUX8 With SUSI interface	each 150 mA each 300 mA unamplified *) unamplified *) unamplified *) X
Connecting option 21 pin socket board for direct plugging (NEM660/RCN-121)	DH21B-5

\*) Unamplified function outputs: See supplement 3.



#### DH21B-5

21 piii iiiteriace			
GPIO	1	22	G1
*) AUX7	2	21	G2
*) AUX6	3	20	GND
*) AUX4	4	19	M1
ZCLK	5	18	M2
ZDAT	6	17	AUX5 *)
LR	7	16	VS
LV	8	15	AUX1
	9	14	AUX2
	10	13	AUX3 *)
Index	11	12	VCC

21 nin interface

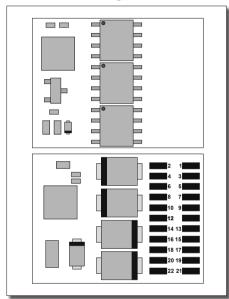
<b>M1, M2</b> Motor connection 1, 2
<b>G1, G2</b> Track connection 1, 2
<b>LV, LR</b> Front light, rear light (each 150 mA)
AUX1, AUX2 Additional function 1, 2 (each 300 mA)
AUX3 AUX7 Unamplified function *)
<b>VS</b> Supply voltage
<b>ZVS</b> SUSI supply voltage
ZCLKSUSI clock
ZDAT SUSI data
<b>GND</b> Ground (0 V)
<b>GPIO</b> General input / output (max. +5 V / max. 3 mA)
or AUX8 unamplified *)
<b>VCC</b> +5 V / max. 15 mA

<sup>\*)</sup> Unamplified function outputs: See supplement 3.

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).



# DH22A (1st generation)



Specifications	DH22A
Dimensions [mm] Total load Maximum motor current	20,7 x 15,8 x 5,2 2,0 A 2,0 A
Maximum operating voltage Switching voltage at AC analog: Max. 45 V peak = 30 V eff.	30 V X
Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4	each 150 mA each 300 mA each 1,0 A
Function outputs: AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated)	unamplified *)
Connecting option 22 pin connector for direct plugging (PluX22)	DH22A-4

<sup>\*)</sup> Unamplified function outputs: See supplement 3.



#### DH22A (1st generation)

#### PluX22 interface

GPIO	1	2	AUX3
ZCLK	3	4	ZDAT
GND	5	6	ZVS
LV	7	8	M1
VS	9	10	M2
Index	11	12	G1
LR	13	14	G2
	15	16	AUX1
	17	18	AUX2
AUX4	19	20	_
_	21	22	-

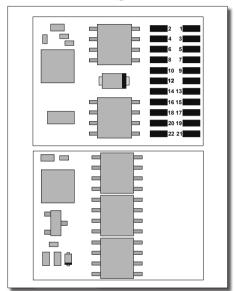
M1, M2	. Motor connection 1, 2
G1, G2	. Track connection 1, 2
LV, LR	. Front light, rear light (each 150 mA)
AUX1, AUX2	. Additional function 1, 2 (each 300 mA)
AUX3, AUX4	.Unamplified function 3, 4 (each 1,0 A)
VS	. Supply voltage
<b>ZVS</b>	. SUSI supply voltage
ZCLK	. SUSI clock (or AUX5 unamplified) *)
ZDAT	. SUSI data (or AUX6 unamplified) *)
GND	. Ground (0 V)
GPIO	. General input / output (max. +5 V / max. 3 mA)

<sup>\*)</sup> Unamplified function outputs: See supplement 3.

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).



# DH22A (2<sup>nd</sup> generation)



Specifications	DH22A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Switching voltage at AC analog: Max. 45 V peak = 30 V eff. Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 Function outputs: AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated)	20,7 x 15,8 x 5,2 2,0 A 2,0 A 30 V X each 150 mA each 300 mA each 1,0 A unamplified *)
Connecting option 22 pin connector for direct plugging (PluX22)	DH22A-4

<sup>\*)</sup> Unamplified function outputs: See supplement 3.



## DH22A (2<sup>nd</sup> generation)

#### PluX22 interface

GPIO	1	2	AUX3
ZCLK	3	4	ZDAT
GND	5	6	ZVS
LV	7	8	M1
VS	9	10	M2
Index	11	12	G1
LR	13	14	G2
	15	16	AUX1
	17	18	AUX2
AUX4	19	20	_
_	21	22	_

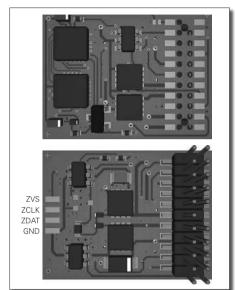
<b>M1, M2</b> Motor connection 1, 2
<b>G1, G2</b> Track connection 1, 2
LV, LR Front light, rear light (each 150 mA)
AUX1, AUX2 Additional function 1, 2 (each 300 mA)
AUX3, AUX4 Unamplified function 3, 4 (each 1,0 A)
VSSupply voltage
<b>ZVS</b> SUSI supply voltage
<b>ZCLK</b> SUSI clock (or AUX5 unamplified) *)
ZDAT SUSI data (or AUX6 unamplified) *)
<b>GND</b> Ground (0 V)
<b>GPIO</b> General input / output (max. +5 V / max. 3 mA)

<sup>\*)</sup> Unamplified function outputs: See supplement 3.

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).



# DH22B



Specifications	DH22B
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Switching voltage at AC analog: Max. 45 V peak = 30 V eff. Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 Function outputs: AUX5, AUX6, AUX7 Function output: AUX8 With SUSI interface	20,7 x 15,8 x 5,2 2,0 A 2,0 A 30 V X each 150 mA each 300 mA each 1,0 A each 1,0 A unamplified *)
Connecting options Without connection wire With connection cable for interface per NEM652 With connection wires 22 pin connector for direct plugging (PluX22)	DH22B-0 DH22B-2 DH22B-3 DH22B-4

<sup>\*)</sup> Unamplified function outputs: See supplement 3.



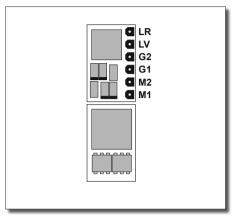
#### DH22B

PluX22 interface		M1, M2	Motor connection 1, 2		
		G1, G2	Track connection 1, 2		
GPIO	1	2	AUX3	LV, LR	Front light, rear light (each 150 mA)
ZCLK	3	4	ZDAT	AUX1, AUX2	Additional function 1, 2 (each 300 mA)
GND	5	6	ZVS	AUX3 AUX7	Additional function 3 7 (each 1,0 A)
LV	7	8	M1	VS	Supply voltage
VS	9	10	M2	ZVS	SUSI supply voltage
Index	11	12	G1	ZCLK	SUSI clock
LR	13	14	G2	ZDAT	SUSI data
	15	16	AUX1	GND	Ground (0 V)
	17	18	AUX2	GPIO	General input / output (max. +5 V / max. 3 mA)
AUX4	19	20	AUX5		or AUX8 unamplified *)
AUX6	21	22	AUX7	*) Unamplified fur	nction outputs: See supplement 3.

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).



# PD05A (1st generation)



Specifications	PD05A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable)	5,0 x 7,9 x 2,5 0,5 A 0,5 A <b>18 V</b> each 150 mA
Connecting options Without connection wires With ribbon cable for interface per NEM651 With connection wires	PD05A-0 PD05A-1 PD05A-3

**M1, M2**...... Motor connection 1, 2

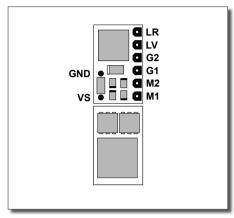
G1, G2...... Track connection 1, 2

LV, LR ...... Front light, rear light (each 150 mA)

There is no connection possibility (VS) for the common return conductor (blue wire) or a buffer capacitor.



# PD05A (2<sup>nd</sup> generation)



Specifications	PD05A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable)	5,2 x 8,0 x 2,5 0,5 A 0,5 A 30 V each 150 mA
Connecting options Without connection wires With ribbon cable for interface per NEM651 With connection wires 6 pin connector for direct plugging (NEM651)	PD05A-0 PD05A-1 PD05A-3 PD05A-4

**M1, M2**...... Motor connection 1, 2

G1, G2...... Track connection 1, 2

LV, LR ...... Front light, rear light (each 150 mA)

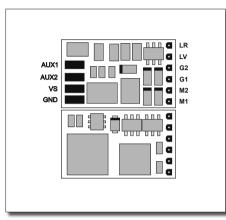
**VS**.....Supply voltage **GND** ......Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS.

You can connect a buffer capacitor to VS (+) and GND (-).



#### PD06A



Specifications	PD06A
Dimensions [mm] Total load Motor voltage Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable)	6,8 x 11,4 x 2,8 0,5 A 6 V 0,2 A <b>18 V</b> each 150 mA each 300 mA
Connecting options Without connection wires With connection wires	PD06A-0 PD06A-3

**M1, M2**..... Motor connection 1, 2

**G1, G2**.....Track connection 1, 2

LV, LR .....Front light, rear light (each 150 mA)

AUX1, AUX2..... Additional function 1, 2 (each 300 mA)

**VS**.....Supply voltage

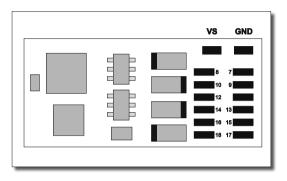
**GND** ...... Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS.

You can connect a buffer capacitor to VS (+) and GND (-).



#### PD12A



Specifications	PD12A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable)	24,2 x 11,0 x 2,4 1,0 A 1,0 A 30 V each 150 mA each 300 mA
Connecting options Without connection wires With connection cable for interface per NEM652 With connection wires 12 pin connector for direct plugging (PluX12)	PD12A-0 PD12A-2 PD12A-3 PD12A-4

**VS**.....Supply voltage

**GND** ...... Ground (0 V)

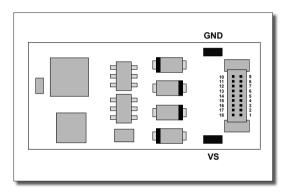
If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to VS (+) and GND (-).

#### PluX12-Interface

	1	2	
	3	4	
	5	6	
LV	7	8	M1
VS	9	10	M2
ndex	11	12	G1
LR	13	14	G2
	15	16	AUX1
	17	18	AUX2
	19	20	
	21	22	



#### PD18A



Specifications	PD18A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable)	23,8 x 10,8 x 2,0 1,0 A 1,0 A 30 V each 150 mA each 300 mA
Connecting option 18 pin connector for direct plugging (Next18)	PD18A

**M1, M2**..... Motor connection 1, 2

**G1, G2**.....Track connection 1, 2

LV, LR .....Front light, rear light (each 150 mA)

AUX1, AUX2..... Additional function 1, 2 (each 300 mA)

**VS**.....Supply voltage

**GND** ...... Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS.

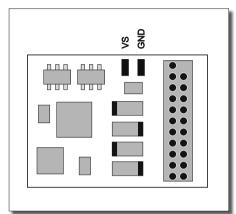
You can connect a buffer capacitor to VS (+) and GND (-).

#### Next18 interface

			_
G1	1	18	G1
M1	2	17	LR
AUX1	3	16	_
_	4	15	VS
GND	5	14	GND
VS	6	13	_
_	7	12	AUX2
LV	8	11	M2
G2	9	10	G2



#### PD21A



Specifications	PD21A
Dimensions [mm] Total load Maximum motor current Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable)	21,2 x 15,5 x 2,9 1,0 A 1,0 A 30 V each 150 mA each 300 mA
Connecting option 21 pin socket board for direct plugging (mTc21)	PD21A-4

**M1, M2**..... Motor connection 1, 2

G1, G2.....Track connection 1, 2

LV, LR .....Front light, rear light (each 150 mA)

AUX1, AUX2.....Additional function 1, 2 (each 300 mA)

**VS**.....Supply voltage

**GND** ......Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS.

You can connect a buffer capacitor to VS (+) and GND (-).

#### 21 pin interface

_	1	22	G1
_	2	21	G2
	3	20	GND
_	4	19	M1
_	5	18	M2
_	6	17	
LR	7	16	VS
LV	8	15	AUX1
	9	14	AUX2
	10	13	_
Index	11	12	_



#### 5.1 Functions

- Operation can be controlled either by conventional DC command stations or by digital central units supporting the formats SelecTRIX 1 and 2, DCC format or MM1/MM2 standard
- Automatic switch over from conventional DC to digital operation
- In case of digital operation the last programmed system will be activated. Automatic switching into a certain operating mode is not possible because of the multiprotocol operation. For switching a parameter (e.g. locomotive address) is to be readout and must be written again in the required operating mode. Thus the switching to the required track protocol is completed.
- SelecTRIX 1..... 31 speed steps, 100 addresses
- SelecTRIX 2..... 127 speed steps, 10.000 addresses, 16 additional functions
- DCC ...... short addresses (1-127), long addresses (0001-9999), with 14, 28, 126 speed steps
- State of art load regulation, in this way an especially smooth control mode
- Different control variants for an optimal adaption to the motor
- 127 internal speed steps
- Adjustable motor frequency (low frequency, 16 kHz, 32 kHz)
- Block section operation by simple diodes in digital operation
- Light and function outputs are (partly) dimmable and can be activated analogously
- Shunting gear
- Motor, light and track connections electronically changeable
- All function outputs are freely programmable
- Thermal protection
- Reset function for DCC and SX2
- Updateability of the decoder

The update (free software download from the internet) is possible in the installed state of the decoder on the track (no need to open the engin) and is done either via the FCC digital centre or the programmer. If no corresponding hardware is available, the company Doehler & Haass will provide a programmer on loan on request.

Decoders support braking with asymmetric digital voltage (four diodes connected in series and one antiparallel diode), slow approach (with appropriate brake modules) and the bidirectional communication (locomotive address check back signal in DCC operation, RailCom®).

### 5.1.1 Limitations of the PD series compared to our DH decoder series

The PD05A nano locomotive decoder is an especially small vehicle decoder for SX1, SX2 and DCC operation.

- No support for MM and DC-analog operation modes
- No support of SX1 programming (but SX1 operation is possible through SX2 parameter programming)
- No SUSI interface and no function outputs
- No extended function assignments (i.e.: no conditions, no initial mapping etc.)
- No automatic coupling process
- No brake ramp



# The PD06A vehicle decoder for miniature motors is our particularly small vehicle decoder for SX1, SX2 and DCC operation.

- No support for MM mode
- No support of SX1 programming (but SX1 operation is possible through SX2 parameter programming)
- No SUSI interface
- No extended function assignments (i.e.: no conditions, no initial mapping etc.)
- No automatic coupling process
- No braking with asymmetrical digital voltage and no slow driving
- No brake ramp

# The PD12A, PD18A and PD21A vehicle decoders are particularly inexpensive vehicle decoders for pure DCC operation and DC analog.

- No support of the operating modes SX1, SX2 and MM
- No SUSI interface and no unamplified function outputs
- No extended function assignments (i.e.: no conditions, no initial mapping etc.)
- No automatic coupling process (but timers for switching off AUX1 and AUX2 are available)

### 5.2 Installation of the decoder

Before installation check if the locomotive is in perfect electrical and mechanical condition. Defects and dirt must be eliminated first. Pay attention to the instructions of the locomotive producer.

Only locomotives running smoothly in analogue mode should be equipped with digital decoder. New locomotives should be run in at least 30 minutes in each driving direction.

Before starting installation, insulate the motor and all its terminals completely against track connections (sliders, chassis etc.).

### Both motor connections must be disconnected from the ground!

Further on all capacitors have to be removed, particularly those associated with the connections of light and motor.

Fix the decoder with a double sided adhesive tape.

### 5.3 Connection of the decoder

### Wired variants:

- 1 The decoders DH05C-**0**, DH10C-**0**, DH16A-**0**, DH21A-**0**, DH22B-**0**, PD05A-**0**, PD06A-**0** and PD12A-**0**, should be used by experienced model railroaders only, as the connection wires must be soldered directly onto the decoder.
- 2 In case your locomotive is equipped with an interface according to NEM 651, you should take the decoder DH05C-1, DH10C-1, DH10C-2, DH10C-4 or PD05A-1. They have already the appropriate connections for this plug. Short the ribbon cable up to 5 mm and remove the rest of insulation. The decoder can be inserted into the interface without any problem now.
- In case your locomotive is equipped with an interface according to NEM 652, you should take the decoder DH16A-2, DH21A-2, DH22B-2 or PD12A-2. They have already the appropriate connections for this plug with an 8 pin plug. The decoder can be inserted into the interface without any problem now.
- 4 In case your locomotive is not equipped with an interface jack, the decoders must be wired individually. For this purpose you should use the decoders DH05C-3, DH10C-3, DH16A-3, DH21A-3, DH22B-3, PD05A-3, PD06A-3 or PD12A-3 with flexible wires.

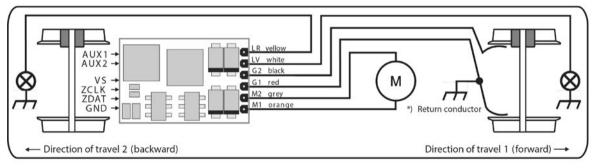


### Variants with interfaces:

- In case your locomotive is equipped with a 12 pin interface (PluX12), you should take the decoder DH12A or PD12A-**4**. They have already the appropriate connections for this plug. The decoder can be inserted into the interface without any problem now.
- In case your locomotive is equipped with a 14 pin interface (mTc14), you should take the decoder DH14B. It has already the appropriate connection for this plug. The decoder can be inserted into the interface without any problem now.
- In case your locomotive is equipped with a 16 pin interface (PluX16), you should take the decoder DH16A-**4**. It has already the appropriate connection for this plug. The decoder can be inserted into the interface without any problem now.
- 8 In case your locomotive is equipped with an 18 interface (Next18), you should take the decoder DH18A or PD18A. It has already the appropriate connection for this plug. The decoder can be inserted into the interface without any problem now.
- 9 In case your locomotive is equipped with a 21 pin interface (mtc21), you should take the decoder DH21A/B-4, DH21A/B-5 or PD21A-4. It has already the appropriate connection for this plug. The decoder can be inserted into the interface without any problem now.
- 10 In case your locomotive is equipped with a 22 pin interface (PluX22), you should take the decoder DH22A/B-4. It has already the appropriate connection for this plug. The decoder can be inserted into the interface without any problem now.



# For the wired variants connect the wires of the decoder according to the following diagram (see also graphic below)



\*) Depending on the manufacturer, the return conductor can be connected to wheel 1 or 2 (red or black) and to the locomotive chassis



### The wires of an additionally connected SUSI module are connected according to the following scheme:

black wire ...... Ground (GND)

### **Function outputs:**

The function outputs AUX\* are possibly on the underside of the decoder and must be connected to the consumer with individual wires or – if unamplified – via appropriate amplifiers.

### Notice:

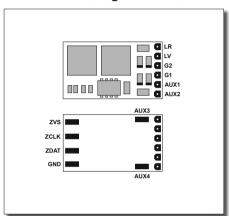
In case of an incorrect wiring of motor, lighting and track, there is no need to solder off the wires as the assignment can be interchanged electronically by programming (see setting options of the respective system format: CV51 or par031, par032, par033).

#### 5.4 Check after installation

The first test should be made in programming mode (e.g. by reading out the address). If there is not correct check back signal to the central unit ("Error"), check again the mapping of the connection or the electrical separation of the motor from the chassis.

### 6 Vehicle function decoder

### FH05B (1st generation)



Specifications	FH05B
Dimensions [mm] Total load Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4, AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated)	13,7 x 7,8 x 1,5 0,5 A 30 V each 150 mA each 300 mA unamplified *) X
Connecting options Without connection wires With ribbon cable for interface per NEM651 With connection wires	FH05B-0 FH05B-1 FH05B-3

**G1, G2**......Track connection 1, 2 **LV, LR**.....Front light, rear light (each 150 mA) **AUX1, AUX2**....Additional function 1, 2 (each 300 mA) **AUX3, AUX4**....Unamplified function 3, 4 \*)

**ZVS** ......SUSI supply voltage

**ZCLK**......SUSI clock (or AUX5 unamplified) \*) **ZDAT**.....SUSI data (or AUX6 unamplified) \*)

**GND** ...... Ground (0 V)

\*) Unamplified function outputs: See supplement 3.

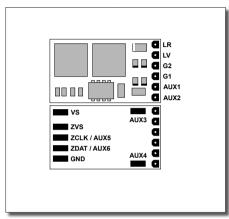
If necessary: Connect blue wire (common return conductor) to ZVS.

You can connect a buffer capacitor to ZVS (+) and GND (-).

Please note that the ZVS connection does not carry voltage in analog mode.



### FH05B (2<sup>nd</sup> generation)



Specifications	FH05B
Dimensions [mm] Total load Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4, AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated)	13,4 x 7,8 x 1,7 0,5 A 30 V each 150 mA each 300 mA unamplified *) X
Connecting options Without connection wires With ribbon cable for interface per NEM651 With connection wires	FH05B-0 FH05B-1 FH05B-3

**G1, G2** ..... Track connection 1, 2

LV, LR .....Front light, rear light (each 150 mA)

AUX1, AUX2..... Additional function 1, 2 (each 300 mA)

AUX3, AUX4..... Unamplified function 3, 4 \*)

**ZVS** ......SUSI supply voltage

ZCLK/AUX5 ...... SUSI clock (or AUX5 unamplified) \*)

ZDAT/AUX6......SUSI data (or AUX6 unamplified) \*)

**GND** ..... Ground (0 V)

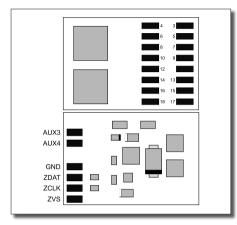
\*) Unamplified function outputs: See supplement 3.

If necessary: Connect blue wire (common return conductor) to VS.

You can connect a buffer capacitor to ZVS (+) and GND (-).



### FH16A



Specifications	FH16A
Dimensions [mm] Total load Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 Function outputs: AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated)	after publication 1,5 A 30 V each 150 mA each 300 mA each 1,0 A unamplified *)
Connecting option 16 pin connector for direct plugging (PluX16)	FH16A-4

\*) Unamplified function outputs: See supplement 3.

**G1, G2**.....Track connection 1, 2

LV, LR .....Front light, rear light (each 150 mA)

AUX1, AUX2..... Additional function 1, 2 (each 300 mA)

AUX3, AUX4.....Additional function 3, 4 (each 1,0 A)

VS.....Supply voltage

**ZVS** ......SUSI supply voltage

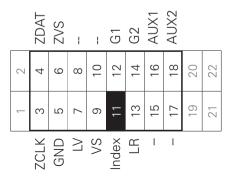
ZCLK.....SUSI clock (or AUX5 unamplified) \*)

**ZDAT** ......SUSI data (or AUX6 unamplified) \*)

**GND** ...... Ground (0 V)

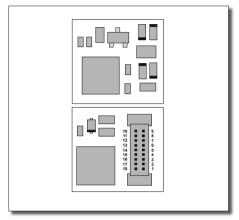
If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).

### PluX16 interface





## FH18A (1st generation)



Specifications	FH18A
Dimensions [mm] Total load Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4, AUX5, AUX6 With SUSI interface (if AUX3/AUX4 deactivated)	10,4 x 9,7 x 3,2 1,0 A 30 V each 150 mA each 300 mA unamplified *) X
Connecting option 18 pin connector for direct plugging (Next18)	FH18A

\*) Unamplified function outputs: See supplement 3.

### **Next18 interface**

G1	1	18	G1
_	2	17	LR
AUX1	3	16	AUX5 *
ZCLK	4	15	VS
GND	5	14	GND
VS	6	13	ZDAT
*) AUX6	7	12	AUX2
LV	8	11	] _
G2	9	10	G2

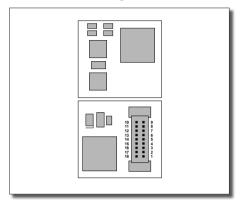
G1, G2	.Track connection 1, 2
LV, LR	.Front light, rear light (each 150 mA)
AUX1, AUX2	. Additional function 1, 2 (each 300 mA)
AUX5, AUX6	.Unamplified function 5, 6 *)
VS	. Supply voltage (also for SUSI)
ZCLK	.SUSI clock (or AUX3 unamplified) *)
ZDAT	.SUSI data (or AUX4 unamplified) *)
GND	. Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to VS (+) and GND (-).



## **Notes**

### FH18A (2<sup>nd</sup> generation)



Specifications	FH18A
Dimensions [mm] Total load Maximum operating voltage Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4, AUX5, AUX6 With SUSI interface (if AUX3/AUX4 deactivated)	9,7 x 8,9 x 2,8 1,5 A 30 V each 150 mA each 300 mA unamplified *) X
Connecting option 18 pin connector for direct plugging (Next18)	FH18A

\*) Unamplified function outputs: See supplement 3.

### **Next18 interface**

G1	1	18	G1
_	2	17	LR
AUX1	3	16	AUX5 *)
ZCLK	4	15	VS
GND	5	14	GND
VS	6	13	ZDAT
*) AUX6	7	12	AUX2
LV	8	11	_
G2	9	10	G2
			•

G1, G2	Irack	connection	า 1, 2
	_		

**LV, LR** ..... Front light, rear light (each 150 mA)

AUX1, AUX2..... Additional function 1, 2 (each 300 mA)

AUX5, AUX6..... Unamplified function 5, 6 \*)

**VS**.....Supply voltage (also for SUSI)

ZCLK.....SUSI clock (or AUX3 unamplified) \*)

**ZDAT** ......SUSI data (or AUX4 unamplified) \*)

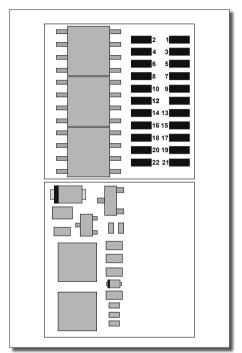
**GND** ...... Ground (0 V)

If necessary: Connect blue wire (common return conductor) to VS.

You can connect a buffer capacitor to VS (+) and GND (-).



## FH22A



Specifications	FH22A
Dimensions [mm] Total load Maximum operating voltage Switching voltage at AC analog: Max. 45 V peak = 30 V eff.	16,1 x 15,8 x 3,3 2,0 A 30 V X
Function outputs for light: LV, LR (dimmable) Function outputs: AUX1, AUX2 (dimmable) Function outputs: AUX3, AUX4 Function outputs: AUX5, AUX6 With SUSI interface (if AUX5/AUX6 deactivated)	each 150 mA each 300 mA each 1,0 A unamplified *)
Connecting option 22 pin connector for direct plugging (PluX22)	FH22A-4

<sup>\*)</sup> Unamplified function outputs: See supplement 3.

### FH22A

### PluX22 interface

GPIO	1	2	AUX3
ZCLK	3	4	ZDAT
GND	5	6	ZVS
LV	7	8	_
VS	9	10	_
Index	11	12	G1
LR	13	14	G2
	15	16	AUX1
	17	18	AUX2
AUX4	19	20	_
_	21	22	_

<b>G1, G2</b> Tra	ack connection 1, 2
<b>LV, LR</b> Fro	ont light, rear light (each 150 mA)
<b>AUX1, AUX2</b> Ac	Iditional function 1, 2 (each 300 mA)
AUX3, AUX4 Ac	lditional function 3, 4 (each 1,0 A)
<b>VS</b> Su	ipply voltage
<b>ZVS</b> SU	JSI supply voltage
<b>ZCLK</b> SU	JSI clock (or AUX5 unamplified) *)
<b>ZDAT</b> SU	JSI data (or AUX6 unamplified) *)
<b>GND</b> Gr	ound (0 V)
<b>GPIO</b> Ge	eneral input / output (max. +5 V / max. 3 mA)

<sup>\*)</sup> Unamplified function outputs: See supplement 3.

If necessary: Connect blue wire (common return conductor) to VS. You can connect a buffer capacitor to ZVS (+) and GND (-).



### 6.1 Functions

- Operation can be controlled either by conventional DC command stations or by digital central units supporting the formats SelecTRIX 1 and 2, DCC format or MM1/MM2 standard.
- Automatic switchover from conventional DC to digital operation.
- In case of digital operation the last programmed system will be activated. Automatic switching into a certain operating mode is not possible because of the multi protocol operation. For switching a parameter (e.g. the locomotive address) is to be readout and must be written again in the required operating mode. Thus the switching to the required track protocol is completed.
- SelecTRIX 1..... 31 speed steps, 100 addresses
- SelecTRIX 2..... 127 speed steps, 10.000 addresses, 16 additional functions
- DCC......short addresses (1-127), long addresses (0001-9999), with 14, 28, 126 speed steps
- 127 internal speed steps
- Block section operation by simple diodes in digital operation
- Light and function outputs are (partly) dimmable and can be activated analogously
- Shuntig gear
- Light and track connections are electronical changeable
- All function outputs are freely programmable
- Thermal protection
- Reset function for DCC and SX2
- The decoder can be uptdated

The update (the firmware download from the Internet is free of charge) is possible while the decoder is installed on the track (no need to open the engine) and is done either via the FCC digital control center or the programmer. If no appropriate hardware is available, the company Doehler & Haass will provide a programmer on loan on request.

The vehicle function decoder support braking system with asymmetric digital voltage (four diodes connected in series and one antiparallel diode), slow approach (with appropriate brake modules) and the bidirectional communication (locomotive address check back signal in DCC operation, RailCom®).



The vehicle function decoder correspond functionally completely with the decoders described in point 5. Only features in direct connection with the engine control are missing. This fact is marked in the setting options of the corresponding system format. See:

- Point 7.2
- Point 8.2: CV09, CV49, CV50, CV51/Bit 0, CV56 CV59, CV112
- Point 10.2: par017, par032, par052 par054, par056 par059

### 6.2 Installation of the vehicle function decoder

See notice in point 5.2.

# 6.3 Connection of the vehicle function decoder Wired variants:

- 1 The FH05B-**0** decoder should only be used by experienced model railroaders, as the connecting wires must be soldered directly onto the decoder.
- 2 In case your model is equipped with an interface according to NEM 651, you should take the decoder FH05B-1. It has already the appropriate connections for this plug. Short the ribbon cable up to 5 mm and remove the rest of insulation. The decoder can be inserted into the interface without any problem now.
- 3 In case your model is not equipped with an interface jack, the decoder must be wired individually. For this purpose you should use the decoder FH05B-3 with flexible wires.

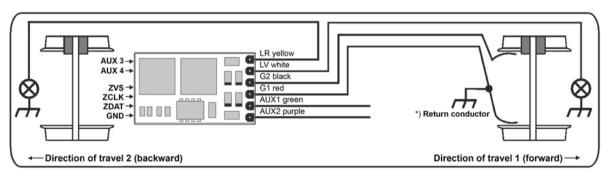
#### Variants with interfaces:

4 In case your model is equipped with a 16 pin interface (PluX16), you should take the decoder FH16A-**4**. It has already the appropriate connection for this plug. The decoder can be inserted into the interface without any problem now.



- In case your model is equipped with an 18 interface (Next18), you should take the decoder FH18A. It has already the appropriate connection for this plug. The decoder can be inserted into the interface without any problem now.
- In case your model is equipped with a 22 pin interface (PluX22), you should take the decoder FH22A-**4**. It has already the appropriate connection for this plug. The decoder can be inserted into the interface without any problem now.

# For the wired versions, connect the wires of the decoder according to the following diagram (see also graphic below):



\*) Depending on the manufacturer, the return conductor can be connected to wheel 1 or 2 (red or black) and to the locomotive chassis.



### The wires of an additionally connected SUSI module are connected according to the following scheme:

red wire ...... SUSI supply voltage (ZVS) or supply voltage (VS) if no ZVS available

### **Function outputs:**

The function outputs AUX\* may be located on the underside of the decoder and must be connected to the consumers with extra wires or - if unamplified - via suitable amplifiers.

### Notice:

In case of an incorrect wiring of the light or track wire, there is no need to solder off the wires, as the assignement can be interchanged electronically by programming (see setting options of the respective system format: CV51 or. par031, par033).

#### 6.4 Check after installation

See notice in point 5.4.



# 7 System formate SelecTRIX 1 (SX1)

### 7.1 Functions

Speed steps31	
Speed steps (internal)127	
Front light/rear lightyes	
Additional functions2	
Functions in additional channel8	(connectable with locomotive address + 1)
Operation with brake diodesyes	
Locomotive number outputves	

## 7.2 Setting options

All locomotive parameters can be varied by programming freely at any time. Please take the programming informations out of the instructions of your programming device.

Instructions for "Function Mapping" by default see Doehler & Haass website: https://doehler-haass.de/cms/pages/haeufige-fragen.php

Wie sieht das standardmäßige "Function Mapping" aus? (only in German)



-	
Rasic	settings
Dusio	Settings

Interchange track connections ...... 4

(01) (5) (3) (2)	1 = slow 7 = fast 1 = low 7 = high Not relevant to FH05B/FH16A/FH18A/FH22A
(1)	
0 7	(4)
1 4	(3)
	(4) evant to FH05B/FH16A/FH18A/FH22A
	(5) (3) (2) (1) 0 7 1 7 1 4



Activation of AFB (Automatic acceleration/deceleration control) and additional channel

Function	with AFB	without AFB
Without additional channel	1	2
With ZK*) without function mapping	3	4
With ZK*) with function mapping	5	6
Without ZK*) with function mapping	7	_

<sup>\*)</sup> The additional channel (ZK) has always the address: Locomotive address + 1

Motor control variant	1 4	Not relevant to FH05B/FH16A/FH18A/FH22A
Setting by par056 ff	1	
Hard	2	
Soft	3	
Very soft	4	

Reading out the extended characteristic values is executed by the entry of the character sequence **00–111** and by pressing the programming key. Writing of the extended characteristic values is executed by the entry of the character sequence **00=VAI** and by pressing the programming key.

Notice: Coreless motors should be operated with regulation variant 4 and pulse width 1. No warranty for damages due to incorrect adjustments.

#### Caution!

Reading out and entering exctended characteristic values overwrite the default values of the decoder. In case you have varied the extended characteristic values; the defaul characteristic value of the decoder must be entered again.

### Note for connected SUSI modules:

The supply voltage of the SUSI module (red wire) is connected to the ZVS connection of the decoder: Nothing else needs to be observed.

The supply voltage of the SUSI module (red wire) is connected to the VS terminal of the decoder:

For SX1 programming, a connected SUSI module must be removed. It is sufficient to disconnect the supply voltage of the SUSI module (red wire) for the time of SX1 programming. D&H sound modules (such as SH05A, SH10A etc.) are not affected by this.

## 7.3 Operation

Put the locomotive on the programming track and readout the programming parameters of the decoder. The default value should be 01-532. Program the desired locomotive address and start running the locomotive with those parameter values. After the first check you can vary the parameters of the engine freels to your requirements.

In case your programming device indicates "Error", please check again the correct wiring of the locomotive and pay attention to the wiring instructions for connecting the programming track. **Never put such a locomotive into operation!** 

### 7.4 Explanation of the brake sections

### 1 part brake section:

In front of the signal section one track is controlled by a diode. The decoder must be programmed on 1 part brake section (-). The locomotive decelerates to stop.

### 2 part brake section:

In front of the signal there are two track sections. The first one is controlled by a diode. The locomotive decelerates to internal speed step 3 in this section. The second one is without supply, thus the locomotive stops just in front of the signal. In this case the decoder must be programmed on 2 part brake section (=).



# 8 System format DCC

### 8.1 Functions

Short address	1-127
Long address	0001-9999
Speed steps	14, 28, 126
Speed steps (internal)	127
Front light/rear light (dimmable)	yes
Additional functions (dimmable)	2
Functions total	28
Operation with brake diodes	yes
Operation with brake generators	yes
Consist mode	yes
Programming On The Main	yes
Locomotive number output	yes

### Notice to address range:

DCC operation allows only address values from 1 to 127 for DCC-CV01, operating MM values from 1 to 255 are allowed. Values from 128 on lead to restricting the decoder operation only to MM, i.e. DCC operation is no longer possible. DCC "service mode" is of course still possible.

Activating the long DCC address through CV29/Bit5 makes vice versa that the decoder can be operated by DCC just now. MM operation is no longer possible then. MM programming is also disabled. Attention "lock out" is possible.

### 8.2 Setting options

The features of a locomotive operated in the DCC operating mode can be varied by programming the "Configuration Variables" (CV) freely at any time. The programming procedure is described in the instructions of your programming device.

Instructions for "Function Mapping" by default see Doehler & Haass website: <a href="https://doehler-haass.de/cms/pages/haeufige-fragen.php">https://doehler-haass.de/cms/pages/haeufige-fragen.php</a>

Wie sieht das standardmäßige "Function Mapping" aus? (only in German)

#### Notice:

In case the speed steps programmed on the decoder differ from those of the control device, malfunctions may occur. Please pay attention to the information concerning your digital system.



## 8.2.1 List of supported CV

The abbreviation **FH\*** refers to the decoder types **FH05B**, **FH16A**, **FH18A** and **FH22A**. The abbreviation **PD\*** refers to decoder types **PD05A**, **PD06A**, **PD12A**, **PD18A** and **PD21A**.

CV	Name and definition	Range	Standard
01	Address Addresses higher than 127 are only usable in MM-operation (not relevant to PD*)	1-255	3
02	Starting voltage	0-15	0
03	Acceleration time The value corresponds to the time in seconds from start to maximum speed	0-255	3
04	Deceleration time  The value corresponds to the time in seconds from the maximum speed to stop	0-255	3
05	Maximum speed (see supplement 2)	0-127	92
07	Version number (read only)		
08	Manufacturer identification (read only) 97 = Doehler & Haass (Decoder reset with "8")		
09	Motor frequency         (not relevant to FH*)           Bit         Function         Value           00 = 32 kHz, 1 = 16 kHz	0-15	1



CV	Name and d	definiti	on		Range	Standard
12	MM settings Bit 0-2:  0 = MM-operation deaktivated  1 = MM-operation without additional address  2 = MM-operation with one additional address  3 = MM-operation with two additional address  4 = MM-operation with three additional address  5 = MM-operation with four additional address  6 = MM-operation with five additional address  7 = MM-operation with six additional addresse  Bit 3 = decoder internal use: driving direction a	ses ses ses ses ses		ot relevant to PD	*) 0-15	1
13	0F1       1       4         1F2       2       5         2F3       4       6	5 6	(not <b>Function</b> F5 F6 F7 F8	32 64	A) <b>0-255</b>	1
14	Analog mode F0, F9-F12           Bit         Function         Value         B           0F0 (f)		(not <b>Function</b> F11 F12		A) <b>0-63</b>	3



CV	Name and definition			Standard
17 18	Extended address CV17 contains the most significant byte; CV Only, if activated by CV29/Bit 5=1.	118 contains the least significant byte.	0-255 0-255	195 232
19	Consist address Several compound locomotives run under the 0, 128 = deactivated Value + 128 = inverse direction	nis address (1-127)	0-255	0
21	Consist mode F1-F8           Bit         Function         Value           0F1         1           1F2         2           2F3         4           3F4         8	Bit         Function         Value           4	0-255	0
22	Consist mode F0, F9-F12           Bit         Function         Value           0	Bit         Function         Value           4	0-63	0
27	Brake settings Bit Function Value  0Asymmetry normal	BitFunctionValue4Negative voltage	0-243	64



CV	Name and definition	Range	Standard
28	Check-back settings Bit Function Value  0Channel 1 (Locomotive address) allowed1  1Channel 2 (POM readout etc.) allowed2  2Dynamic channel utilization4	0-7	3
29	Configuration register           Bit         Function         Value           0	0-255	14
33	Function mapping F0(f) (see supp	lement 1) <b>0-255</b>	1
34	Function mapping F0(r) (see supp	lement 1) <b>0-255</b>	2
35	Function mapping F1(f+r) (see supp If CV35 is written, CV47 will be set to the same value	lement 1) <b>0-255</b>	4
36	Function mapping F2(f+r) (see supp If CV36 is written, CV64 will be set to the same value	lement 1) <b>0-255</b>	8
37	Function mapping F3 (see supp	lement 1) <b>0-255</b>	16
38	Function mapping F4 (see supp	lement 1) <b>0-255</b>	128
39	Function mapping F5 (see supp	lement 1) <b>0-255</b>	32
40	Function mapping F6 (see supp	lement 1) <b>0-255</b>	0



CV	Name and definition	Range	Standard
41	Function mapping F7 (see supplement 7	) <b>0-255</b>	0
42	Function mapping F8 (see supplement 7	) <b>0-255</b>	64
43	Function mapping F9 (see supplement 7	) <b>0-255</b>	0
44	Function mapping F10 (see supplement 7	) <b>0-255</b>	0
45	Function mapping F11 (see supplement 7	) <b>0-255</b>	0
46	Function mapping F12 (see supplement 7	) <b>0-255</b>	0
47	Function mapping F1 (r) (see supplement of line case CV47 should have a different value than CV35, you have to set CV35 first and then CV47	0-255	4
48	<b>Speed step characteristic</b> (see supplement 2 Deflection of the speed step characteristic, 0 = linear 7 = strongly curved	2) 0-7	5
49	Impulse width $0 = 1 \text{ ms}, 1 = 2 \text{ ms}, 2 = 4 \text{ ms}, 3 = 8 \text{ ms}$ (not relevant to FH <sup>3</sup> )	0-3	1
50	Control variant (not relevant to FH <sup>3</sup> 0 = defined by CV56 - CV59, 1 = hard, 2 = soft, 3 = very soft	0-3	2
51	Interchange of connections  Bit Function Value  0Motor connections	0-7	0



cv	Name and definition	Range	Standard
52	Dimming LV/LR 0 = dark 31 = full brightness	0-31	31
53	<b>Dimming low beam light</b> (see CV156) 0 = dark 31 = full brightness	0-31	15
54	Dimming AUX1 0 = dark 31 = full brightness	0-31	31
55	Dimming AUX2 0 = dark 31 = full brightness	0-31	31
56	Motor control proportional (not relevant to FH*) Only if CV50 = 0, see: www.doehler-haass.de/"Häufige Fragen" (only in German)	0-7	3
57	Motor control integral (as CV56)	0-3	3
58	Motor control measurement period (as CV56)	0-3	1
59	Motor control impulse width (as CV56)	0-7	3
60	Brake sections 1 or 2	0, 1	0
61	Shuntig gear speed (as CV05)	0-127	63
62	Shunting gear deceleration (as CV03)	0-255	1
63	Starting delay speed step 1 (see CV124) Each 100 ms, 0 = deacitvated	0-250	0
64	Function mapping F2 (r) (see supplement 1) In case CV64 should have a different value than CV36, you must set CV36 first and then CV64	0-255	8



CV	Name and definition	Range	Standard
65	Maximum speed step in two part brake sections Only with brake diode (see CV60)	0-127	12
66	Forward trim 0 = deactivated, smaller 128 = reduction, higher 128 = enhancement of the speed	0-255	0
95	Backward trim (see CV66)	0-255	0
105	User identification 1	0-255	0
106	User identification 2	0-255	0
112	<b>Speed reduction analog</b> (not relevant to FH*/PD05A) 0 = small reduction 31 = strong reduction	0-31	15
113	Switch off function for LV Bit 0 = F1 Bit 7 = F8	0-255	0
114	Switch off function for LR Bit 0 = F1 Bit 7 = F8	0-255	0
115	Switch off function for AUX1 Bit 0 = F1 Bit 7 = F8	0-255	0
116	Switch off function for AUX2 Bit 0 = F1 Bit 7 = F8	0-255	0
117	Timer for switch off AUX1 Each 100 ms, 0 = deactivated	0-250	0
118	Timer for switch off AUX2 Each 100 ms, 0 = deactivated	0-250	0
119	Timer for switch off AUX3 Each 100 ms, 0 = deactivated	0-250	0



CV	Name and definition	Range	Standard
120	Timer for switch off AUX4 Each 100 ms, 0 = deactivated	0-250	0
121	<b>Function mapping LV+LR on / AUX1+AUX2 off</b> Bit 0 = F1 Bit 7 = F8	0-255	0
122	Function mapping AUX1+AUX2 on / LV+LR off Bit $0 = F1 \dots Bit 7 = F8$	0-255	0
123	Slow approach speed Only with suitable brake modules  (see CV27)	0-127	63
124	<b>Function mapping starting delay</b> Bit 0 = F1 Bit 7 = F8	0-255	0
125	Switch off function for AUX3 Bit 0 = F1 Bit 7 = F8	0-255	0
126	Switch off function for AUX4 Bit 0 = F1 Bit 7 = F8	0-255	0
127	Switch off function for AUX5 Bit 0 = F1 Bit 7 = F8	0-255	0
128	Switch off function for AUX6 Bit 0 = F1 Bit 7 = F8	0-255	0
129	Timer for switch off AUX5 Each 100 ms, 0 = deactivated	0-250	0
130	Timer for switch off AUX6 Each 100 ms, 0 = deactivated	0-250	0



CV	Name and definition	Range	Standard
131	<b>Function mapping low beam light</b> (not relevant to PD of the deactivated, 1 28 = F1 F28, 29 = F0 (light) (not relevant to PD of the deactivated) Only valid if CV137/Bit 4=1	*) 0-29	8
132	Function mapping shunting gear (as CV13	1) <b>0-29</b>	4
133	Function mapping deceleration off (as CV13)	<b>0-29</b>	9
134	<b>Decision threshold for asymmetry</b> Default value 6 corresponds approximately to 0.7 volt asymmetry and thus to the forw voltage of a silicon diode. Values smaller 3 are not useful, values higher 6 on demand.	*	6
135	Multiplication speed check back signal 0 = deactivated	0-255	0
136	<b>Division speed check back signal</b> 0 = /1, 1 = /2, 2 = /4, 3 = /8, 4 = /16, 5 = /32, 6 = /64	0-6	0
137	Settings Bit Function Value  0Unamplified function outputs instead of ZCLK and ZDAT *)	0-63	0



CV	Name and definition		Range	Standard
138	<b>Timer for approach</b> Each 100 ms, 0 = no driving away	(not relevant to PD*)	0-250	0
139	<b>Timer for waiting</b> Each 100 ms, 0 = no waiting	(not relevant to PD*)	0-250	0
140	<b>Timer for driving away</b> Each 100 ms, 0 = no driving away	(not relevant to PD*)	0-250	0
141	Speed step for approach	(not relevant to PD*)	0-127	12
142	Speed step for driving away	(not relevant to PD*)	0-127	12
143	Settings Bit Function 6Deactivate coupling process and timer		0-255	0
144	Settings Bit Function  ODynamic channel usage	2 4 8	0-31	0



CV	Name and definitio	n		Range	Standard
145	Conditions for LV		(not relevant to PD*)	0-161	0
	Function	Value			
	Default value (always on, if function key on)	0			
	Only forward	+1			
	Only backward	+2			
	Only while standing	+3			
	Only while driving	+6			
	Only at F0 (light) off	+9			
	Only at F0 (light) on	+18			
	Not in shunting gear	+27			
	Only in shunting gear	+54			
	Ignore direction in shunting gear	+81			
	Ignore driving/stand in shunting gear	+108			
	Ignore direction and driving/stand in shunting gear  Always only one number of each definite range management	+135	lad upl		
		ay be auc	•		_
146	Conditions for LR		(see CV145)	0-161	0
147	Conditions for AUX1		(see CV145)	0-161	0
148	Conditions for AUX2		(see CV145)	0-161	0
149	Conditions for AUX3		(see CV145)	0-161	0
150	Conditions for AUX4		(see CV145)	0-161	0
151	Conditions for AUX5		(see CV145)	0-161	0
152	Conditions for AUX6		(see CV145)	0-161	0



CV	N	ame and definition	Range	Standard
153	38 These function outputs are active a	(not relevant to PD*)  Bit Function Value  4AUX3		0
154	Brake ramp forward and backwall Recommended for constant brakin 0 = deactivated If maximum speed step braking tin steps the decoder generates the b		0	
155	Brake ramp backward 0 = value from CV154 is used Alows different brake times forwar	(see CV154) d and backward	0-255	0
156	Dimming mask for low beam light           Bit         Function         Value           0LV	Bit Function Value 4 Currently without function 16 5 Currently without function 32 6 Currently without function 64 7 Currently without function 128	0-15	3
157	Conditions for low beam light	(see CV145	0-161	0



CV	Name and definition		Range	Standard
260	Manufacturer indentification 97 = Doehler & Haass (Decoder reset with "101")	(read only)		
261	<b>Decoder number</b> FH05B = 41, DH05C = 52, DH10C = 102, DH12A = 120, PD PD05A = 131, PD06A = 132, PD21A = 133, PD18A = 134, DI FH18A = 170, DH18A = 180, FH22A = 192, DH21A = 200, I Complete table see: www.doehler-haass.de/"Häufige Frage	H14B = 141, DH16A = 160, DH22A = 202		
262	Version number	(read only)		
263	Date	(read only)		
264	Revision number	(read only)		
265	Date	(read only)		
401	Function interchange F1 0 = deactivated, 1 28 = F1 F28, 29 = F0 (light)	(not relevant to PD*)	0-29	1
402	Function interchange F2	(as CV401)	0-29	2
403	Function interchange F3	(as CV401)	0-29	3
404	Function interchange F4	(as CV401)	0-29	4
405	Function interchange F5	(as CV401)	0-29	5
406	Function interchange F6	(as CV401)	0-29	6
407	Function interchange F7	(as CV401)	0-29	7
408	Function interchange F8	(as CV401)	0-29	8



CV	Name and definition	Range	Standard
409	Function interchange F9 (as CV401)	0-29	9
410	Function interchange F10 (as CV401)	0-29	10
411	Function interchange F11 (as CV401)	0-29	11
412	Function interchange F12 (as CV401)	0-29	12



#### 8.3 Operation

Put the locomotive on the programming track and readout the locomotive address (CV01). The default value should be 3. Program the desired locomotive address and start running the locomotive keeping these setting values. After the first check you can vary the parameters of the engine freely according to your requirements.

In case your programming device indicates "Error", please check again the correct wiring of the locomotive and pay attention to the wiring instructions for connecting the programming track. **Never put such a locomotive into operation!** 

#### Notice:

Operation with asymmetry in the brake section is not possible with the factory settings.

In case you want this opition, CV27 / bit 0 and/or bit 1 must be set to "1".

Brake section operation in direct current operating mode is not possible with the factory settings.

In case you want this option, CV27 / bit 4 and/or bit 5 must be set to "1".

### 9 Operationsform Märklin-Motorola (MM)

#### 9.1 Functions

Addresses	1-255
Speed steps	14, 28
Speed steps (internal)	127
Front light/rear light (dimmable)	yes
Additional functions (dimmable)	2
Functions total (only MM2)	12
Operation with MM brake section	yes

Instructions for "Function Mapping" by default see: Doehler & Haass website:

https://doehler-haass.de/cms/pages/haeufige-fragen.php

Wie sieht das standardmäßige "Function Mapping" aus? (only in German)

Notice to address range:

In MM operation address values from 1 to 255 are allowed. In DCC operation for DCC CV01 only values from 1 to 127 are allowed. Values from 128 lead to operating the decoder only by MM, i.e. DCC operation is no longer possible. DCC "Service Mode" is still possible.

Conversely, activating the long DCC address with CV29/Bit5 means that the decoder can only be operated with DCC. Then MM operation is no longer possible and MM programming is also disabled. Attention, because "Lock out" is possible.

#### 9.2 Programming with Märklin central unit 6020/6021

- 1 **,Short'** programming allows entering figures between 0 and 79, i.e. in short mode just setup parameters with values from < 80 can be changed, if the desired value should also be < 80.
- 2 **,Long'** programming allows entering figures between 0 and 255, i.e. in long mode all setup parameters with values from 0 to 255 can be changed. As the display of 6020/6021 allows only binary values, the inserting values must be devided and entered in two steps.
- 3 Programming of SUSI parameters Programming of SUSI parameters.

Please notice that 6021/6020 allows only entering values from 01 to 80. Value 0 is missing. **Instead of ,0' always ,80' must be entered.** 

#### Changing to programming mode

- The driving controller must display 0. There may not be other locomotives on the layout. Notice the flashing signal of the locomotive!
- Push STOP and GO button of 6021 simultanously until reset will be triggered (alternatively: disconnect for a moment the plug of the transformer). Push STOP button for disconnecting the track power.
- Enter the current decoder address. If you dont know the address, enter ,80'.



- Revert the driving direction with the driving controller (turn the driving controller to the left beyond the keystroke until your hear a click), hold the controller and and push GO button.
- After about one second the lights of the engine are flashing, the decoder is now in programming mode.

#### Short mode

- After changing in programming mode the decoder is in short mode. The engine lighting flashes slowly and periodically.
- Enter now the number of the CV you want to change, e.g. 01 (double digit).
- Activate the reversion of the driving direction for confirmation. Lighting is now flashing shortly two times.
- Enter now the new value for the CV, e.g. 15 (double digit).
- Activate the reversion of the driving direction for confirmation.
   The lighting flashes.
- You may now enter further CV values which you want to change.

The programming mode is left by selection of CV80 or by turning off and on the track power (push STOP button and then again GO button).

#### Long mode

- You get the longe mode by entering in short mode value 07 in CV07 at first. The decoder confirms changing in long mode by slow fashing of the lighting.
- Enter now then hundredth and ten's digit of the CV, which you want to change. Example: CV124 should be changed: Enter '12'.
- Activate the reversion of the driving direction for confirmation. The lighting flashes long and short (periodically).
- Enter now the unit place of the CV in double digit. See example: '04'.
- Activate the reversion of the driving direction for confirmation. The lighting flashes long short short (periodically). The decoder waits now for entering the CV value.

- Enter now the hundredth and ten's digit of the new CV value. Example: Value 135 is to be written: Enter '13'.
- Activate the reversion of the driving direction for confirmation. The lighting flashes long short short short (periodically)
- Enter now the unit place of the new CV in double digit. Example: Enter '05'.
- Activate the reversion of the driving direction for confirmation. Then the locomotive is flashing again.
- You may now enter further CVs in long mode which you want to change

The long mode can be left by switching the track voltage off and on again or by STOP.

#### SUSI mode

You gain the SUSI mode by writing value 09 in CV09 in short mode.

The decoder confirms that by slow flashing.

Enter CVs respective the related values as in long mode and reduce all CVs about 900.

Thus changes CV903 to 003 for example.

Notice please that you are operating in SUSI mode, which is programmed according to the long mode.

#### Notice:

It is easier to do the programming under DCC.

Thus programmed values are also valid for MM format.



# 10 System format SelecTRIX 2 (SX2) 10.1 Functions

Speed steps	127
Speed steps (internal)	127
Front light/rear light (dimmable)	yes
Additional functions (dimmable)	2
Functions total	16
Operation with brake diodes	yes
Programming On The Main	yes

#### 10.2 Setting options

The features of a locomotive operated in SX2 operating mode can be varied by programming the parameters (par) freels at any time. The programming procedure is described in the instructions of your programming device.

Information on the standard "Function Mapping" can be found on the Doehler & Haass website: <a href="https://doehler-haass.de/cms/pages/haeufige-fragen.php">https://doehler-haass.de/cms/pages/haeufige-fragen.php</a>

Wie sieht das standardmäßige "Function Mapping" aus? (only in German)

### 10.2.1 List of supported parameters

The abbreviation FH\* refers to the decoder types FH05B, FH16A, FH18A and FH22A.

par	Name and definition	Range	Standard
001	Address unit position	0-99	1
002	Address hundreds digit	0-99	10
003	Address for SX1 If > 111 deactivated	0-255	112
004	Address for SX1, 1. additional channel Functions F1-F8	0-255	1
005	Address for SX1, 2. additional channel Functions F9-F16	0-255	0
006	Locomotive address output  1 = activated (if suitable occupancy detectors, power packs/boosters and central units are available).	0-1	0
007	Mode of operation additional channel  0 = relativ:  1. Additional channel = par003 + par004  2. Additional channel = par003 + par005  1 = absolute	0-1	0
800	Consist address unit place Currently without function		



par	Name and definition	Range	Standard
009	Consist address hundreds digit Currently without function		
011	Acceleration time The value corresponds to the time in seconds from start to maximum speed and should be set to at least 8 (s. notice in chapter 10.3)	0-255	3
012	Deceleration time The value corresponds to the time in seconds from the maximum speed to stop and should be set to at least 8 (s. notice in chapter 10.3)	0-255	3
013	Maximum speed (see supplement 2)	0-127	92
014	Starting voltage	0-15	0
015	Slow approach speed step Only with suitable brake modules  (see par091)	0-127	63
016	Start delay speed step 1 (see par095) Each 100 ms, 0 = deactivated	0-250	0
017	<b>Speed reduction analog</b> (not relevant to FH*/PD05A) 0 = small reduction 31 = strong reduction	0-31	15
018	Shunting gear speed (as par013)	0-127	63
019	Shunting gear delay time (as par011)	0-255	1
021	Brake sections 1 or 2	0, 1	0
022	Consist mode F1-F8 Currently without function		



par	Namo	e and definition	Range	Standard
023	Consist mode F0, F9-F12 Currently without function			
024	Switch off function for LV Bit 0 = F1 Bit 7 = F8		0-255	0
025	Switch off function for LR Bit 0 = F1 Bit 7 = F8		0-255	0
026	Switch off function for AUX1 Bit 0 = F1 Bit 7 = F8		0-255	0
027	Switch off function for AUX2 Bit 0 = F1 Bit 7 = F8		0-255	0
028	Analog mode F1-F8         Bit       Function       Value         0	Bit         Function         Value           4F5        16           5F6        32           6F7        64           7F8        128	0-255	1
029	Analog mode F0, F9-F12         Bit       Function       Value         0	Bit         Function         Value           4	0-63	3
031	Interchange of track connections 0 = normal, 1 = interchanged		0, 1	0



par	Name and definition		Range	Standard
032	Interchange of motor connections 0 = normal, 1 = interchanged	(not relevant to FH*)	0, 1	0
033	Interchange of light connections 0 = normal, 1 = interchanged		0, 1	0
043	Settings Bit Function  0 Dynamic channel usage (not relevant to SX1/SX2)  1 Immediate starting after current interruption  2 Special bit for lighting in analog operation  3 Brake section output to "GPIO"	2 4 8	0-31	0
051	<b>Speed step characteristic</b> Deflection of the characteristic curve, 0 = linear 7 = strongle	(see supplement 2) y curved	0-7	5
052	Control variant 0 = defined by par056 ff, 1 = hard, 2 = soft, 3 = very soft	(not relevant to FH*)	0-3	2
053	<b>Impulse width</b> 0 = 1 ms, 1 = 2 ms, 2 = 4 ms, 3 = 8 ms	(not relevant to FH*)	0-3	1



par	Name and definition		Range	Standard
054	Motor frequency Bit Function 00 = 32 kHz, 1 = 16 kHz	2 4	0-15	1
055	Maximum speed step in two part brake sections Only with brake diode	(see par021)	0-127	12
056	Motor control proportional Only if par052 = 0, see: www.doehler-haass.de/,,Häufige Frager	(not relevant to FH*) n" (only in German)	0-7	3
057	Motor control integral	(as par056)	0-3	3
058	Motor control measurement period	(as par056)	0-3	1
059	Motor control impulse width	(as par056)	0-7	3
061	Function mapping F0(f)	(see supplement 1)	0-255	1
062	Function mapping F0(r)	(see supplement 1)	0-255	2
063	Function mapping F1(f+r) If par063 is written, par075 will be set to the same value	(see supplement 1)	0-255	4
064	Function mapping F2(f+r) If par064 is written, par085 will be set to the same value	(see supplement 1)	0-255	8
065	Function mapping F3	(see supplement 1)	0-255	16
066	Function mapping F4	(see supplement 1)	0-255	128
067	Function mapping F5	(see supplement 1)	0-255	32



par	Name and definition		Range	Standard
068	Function mapping F6	(see supplement 1)	0-255	0
069	Function mapping F7	(see supplement 1)	0-255	0
070	Function mapping F8	(see supplement 1)	0-255	64
071	Function mapping F9	(see supplement 1)	0-255	0
072	Function mapping F10	(see supplement 1)	0-255	0
073	Function mapping F11	(see supplement 1)	0-255	0
074	Function mapping F12	(see supplement 1)	0-255	0
075	Function mapping F1(r) In case par075 should have a different value than par063, you must set par063 first and then par075	(see supplement 1)	0-255	4
076	Timer for switch off AUX1 Each 100 ms, 0 = deactivated		0-250	0
077	Timer for switch off AUX2 Each 100 ms, 0 = deactivated		0-250	0
078	Timer for switch off AUX3 Each 100 ms, 0 = deactivated		0-250	0
079	Timer for switch off AUX4 Each 100 ms, 0 = deactivated		0-250	0
081	Dimming LV/LR 0 = dark 31 = full brightness		0-31	31
082	Dimming low beam light 0 = dark 31 = full brightness	(see par089)	0-31	15



par	Name and definition	Range	Standard
083	<b>Dimming AUX1</b> 0 = dark 31 = full brightness	0-31	31
084	<b>Dimming AUX2</b> 0 = dark 31 = full brightness	0-31	31
085	Function mapping F2(r) (see supplement 1) In case par085 should have a different value than par064, you must set par064 first and then par085	0-255	8
086	<b>Function mapping LV+LR on / AUX1+AUX2 off</b> Bit 0 = F1 Bit 7 = F8	0-255	0
087	Function mapping AUX1+AUX2 on / LV+LR off Bit 0 = F1 Bit 7 = F8	0-255	0
088	Settings Bit Function Value  0Unampliefied function outputs instead of ZCLK and ZDAT *)	0-63	0



par	Nan	e and definition	Range	Standard
089	Dimming mask for low beam light           Bit         Function         Value           0LV	(see par082)  Bit Function Value  4 Currently without function 16  5 Currently without function 32  6 Currently without function 64  7 Currently without function 128	0-15	3
091	Brake settings Bit Function Value 0Asymmetry normal1 1Asymmetry invers2 2Currently without function4 3Currently without function8	BitFunctionValue4 Negative voltage	0-243	64
092	Decision threshold for asymmetry Default value 6 corresponds approxim thus to the forward voltage of a silico values greater 6 on demand.	(see par091) ately to 0.7 volt asymmetry and n diode. Values smaller 3 are not useful,	0-15	6
093	Forward trim 0 = deactivated, smaller 128 = reductivated	on, greater 128 = increasing speed	0-255	0
094	Backward trim	(see par093)	0-255	0
095	<b>Function mapping starting delay</b> Bit 0 = F1 Bit 7 = F8	(see par016)	0-255	0



par	Name and definition	Range	Standard
096	Brake ramp forward and backward (see par091, not relevant to PD05A/PD06A) Recommended for constant braking distance: par051 = 0 0 = deactivated If maximum speed step braking time is adjusted in seconds 8 times, at smaller speed steps the decoder generates the brake ramp independently	0-255	0
097	Brake ramp backward (see par096) 0 = value from CV154 is used Allows different brake times forward and backward	0-255	0
098	User identification 1	0-255	0
099	User identification 2	0-255	0
101	Manufacturer number (read only) 97 = Doehler & Haass (Decoder reset with "101")		
102	<b>Decoder number</b> (read only) FH05B = 41, DH05C = 52, DH10C = 102, DH12A = 120, PD12A = 130, PD05A = 131, PD06A = 132, PD21A = 133, PD18A = 134, DH14B = 141, DH16A = 160, FH18A = 170, DH18A = 180, FH22A = 192, DH21A = 200, DH22A = 202 Complete table see: www.doehler-haass.de/,,Häufige Fragen" (only in German)		
103	Version number (read only)		
104	Date (read only)		
105	Revision number (read only)		
106	Date (read only)		
141	Switch off function for AUX3 Bit 0 = F1 Bit 7 = F8	0-255	0



par	Name and definition	on	Range	Standard
142	<b>Switch off function for AUX4</b> Bit 0 = F1 Bit 7 = F8		0-255	0
143	<b>Switch off function for AUX5</b> Bit 0 = F1 Bit 7 = F8		0-255	0
144	<b>Switch off function for AUX6</b> Bit 0 = F1 Bit 7 = F8		0-255	0
145	<b>Timer for switch off AUX5</b> Each 100 ms, 0 = deactivated		0-250	0
146	Timer for switch off AUX6 Each 100 ms, 0 = deactivated		0-250	0
147	Function mapping low beam light 0 = deactivated, 1 28 = F1 F28, 29 = F0 (light) Only valid if par088/Bit 4=1	(not relevant to PD05A/PD06A)	0-29	8
148	Function mapping shunting gear	(as par147)	0-29	4
149	Function mapping deceleration off	(as par147)	0-29	9
151	<b>Timer for approach</b> Each 100 ms, 0 = no approach	(not relevant to PD05A/PD06A)	0-250	0
152	<b>Timer for waiting</b> Each 100 ms, 0 = no waiting	(not relevant to PD05A/PD06A)	0-250	0
153	<b>Timer für driving away</b> Each 100 ms, 0 = no driving away	(not relevant to PD05A/PD06A)	0-250	0
154	Speed steps for approach	(not relevant to PD05A/PD06A)	0-127	12
155	Speed steps for driving away	(not relevant to PD05A/PD06A)	0-127	12



par	Name and definiti	on	Range	Standard
156	Settings Bit Function 6Coupling process and timer deactivated 7Coupling process only in shunting gear		0-255	0
160	Conditions for low beam light	(see par161)	0-161	0
161	Conditions for LV Function Initial state (always on, if function key on ) Only forward Only backward Only while standing Only while driving Only at F0 (light) off Only at F0 (light) on Not in shunting gear Only in shunting gear Ignore direction in shunting gear Ignore driving/stand in shunting gear Always only one number of each definite range of	(not relevant to PD05A/PD06A)  Value  0 +1 +2 +3 +6 +9 +18 +27 +54 +81 +108 +135 may be added up!	0-161	0
162	Conditions for LR	(see par161)	0-161	0
163	Conditions for AUX1	(see par161)	0-161	0
164	Conditions for AUX2	(see par161)	0-161	0
165	Conditions for AUX3	(see par161)	0-161	0



par	Name and definition	Range	Standard
166	Conditions for AUX4 (see par161)	0-250	0
167	Conditions for AUX5 (see par161)	0-127	0
168	Conditions for AUX6 (see par161)	0-127	0
169	Initial mapping (not relevant to PD05A/PD06A)  Bit Function Value  0. LV	0-255	0
401	Function interchange F1 0 = deactivated, 1 28 = F1 F28, 29 = F0 (light)	0-29	1
402	Function interchange F2 (as par401)	0-29	2
403	Function interchange F3 (as par401)	0-29	3
404	Function interchange F4 (as par401)	0-29	4
405	Function interchange F5 (as par401)	0-29	5
406	Function interchange F6 (as par401)	0-29	6
407	Function interchange F7 (as par401)	0-29	7
408	Function interchange F8 (as par401)	0-29	8
409	Function interchange F9 (as par401)	0-29	9



par	Name and definition	Range	Standard
410	Function interchange F10 (as par401)	0-29	10
411	Function interchange F11 (as par401)	0-29	11
412	Function interchange F12 (as par401)	0-29	12

#### 10.3 Operation

Put the locomotive on the programming track and readout the locomotive address of the decoder (par001+par002). The ground value should be 1001. Program the desired locomotive address and start running the locomotive keeping these parameter values. After the first check you can vary the parameters of the engine freely according to your requirements.

In case your programming device indicates "Error", please check again the correct wiring of the locomotive and pay attention to the wiring instructions for connecting the programming track. **Never put such a locomotive into operation!** 



## **Supplement 1: Notes to Function Mapping**

If you want to activate a function enter the value of the corresponding output according to the following table. In case you want to activate several different functions simultaneously you must add up the related values.

#### Output values:

	RG/AUX6	ABL/AUX5	AUX4	AUX3	AUX2	AUX1	LR	LV
Value	128	64	32	16	8	4	2	1

RG = shunting gear ABL = low beam light

**Example:** F4 should activate the shunting gear and switch on the outputs LV and LR:

LV=1, LR=2, RG=128: so you must enter the value 131 in CV38 | par066.

**Notice:** If CV137 I par088 Bit4 is not active (normal mapping):

Value 128 operates the shunting gear, value 64 operates the low beam.

AUX6 and AUX5 are not usable in this case and CV132-134 | par147-149 have no meaning.

If CV137 | par088 bit4 is active (extended mapping): Value 128 operates AUX6, value 64 operates AUX5.

The shunting mode is controlled by CV132 | par147, the low beam is controlled by CV133 | par148.

With CV133 | par149 the delays (CV03, 04 | par011, 012) can be switched off.

**Timer function** 

(CV117-120, 129, 130, par076-079, 145, 146)

Value = 0

The timer is switched off (continuous function)

Value = 1...250

The timer is activated, the coressponding output will be disconnected after the time of:

entered value x 0.1 [sec].

**Switch off function** (CV113-116, CV125-128, par024-027, par141-par144)

This function gives you the option for deactivating the output (e.g. frontal driving cab light off), despite of activated output (e.g. LV by function F0).

**Example:** A typical situation where to apply the switch off function is the push pull operation.

The front lightning pointing to the waggon must be switched off, but the other lights must be reversed according to the driving direction (white  $\leftrightarrow$  red).

FO Switches the light on (white or red according to the driving direction)

F2 Switches the font light off

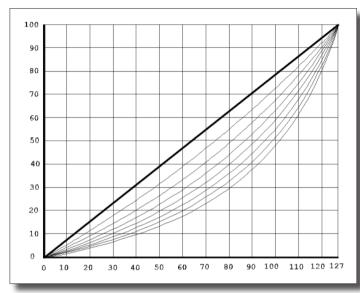
F3 Switches the rear ligth off

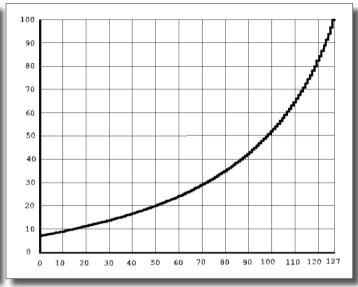
cv	par	Function	RG/ AUX6	ABL/ AUX5	AUX4	AUX3	AUX2	AUX1	LR	LV
33	061	FO(f)					×			X
34	062	FO(r)						X	X	

CV	par	Function	F8	F7	F6	F5	F4	F3	F2	F1
113	024	LV off							X	
114	025	LR off						X		
115	026	AUX1 off							X	
116	027	AUX2 off						X		



## **Supplement 2: Speed characteristics**





Speed step characteristic \*), (see CV48 / par051)

Linear...... 0 Strongly curved...... 7 Maximum speed characteristic (see CV05 / par013) in shunting gear (see CV61 / par018)

<sup>\*)</sup> The curvature of the speed step characteristic corresponds with the DHL locomotive decoder series.

### **Supplement 3: Unamplified function outputs**

As in case the unamplified function outputs (logic level 0 V - 5 V, max. 20 mA) cannot switch higher loads, switching amplifiers (MOSFET, bipolar transistors or the like) must be provided for consumers, which either require a higher supply voltage (> 5 V) or a higher current (> 20 mA).

The SUSI connectors ZCLK and ZDAT can, if available, alternatively always be used as unamplified function outputs:

Explanation for CV137   par088	Bit 5	Bit 4	Bit 0	Value
Activation SUSI interface <b>without</b> extended mapping	0 (or 1)	0	0	0 (or 32)
Activation SUSI interface <b>with</b> extended mapping*	0 (or 1)	1	0	16 (or 48)
ZCLK and ZDAT as unamplified outputs AUX3 and AUX 4 without extended mapping	0	0	1	1
ZCLK and ZDAT as unamplified outputs AUX3 and AUX 4 with extended mapping*	0	1	1	17
ZCLK and ZDAT as unamplified outputs AUX5 and AUX 6 with extended mapping*	1	1	1	49
Deactivation of SUSI interface without extended mapping	1	0	1	33

<sup>\*</sup> See supplement 1

Please note that it does not matter here whether the decoder also offers these function outputs on other solder pads or interfaces! The additional activation of the connectors ZCLK and ZDAT does not change anything on these solder pads or interfaces. If a decoder offers for example AUX3 and AUX4 amplified on corresponding solder pads resp. interfaces, these outputs are additionally available unamplified at the connections ZCLK and ZDAT, if CV137 | par088 is set accordingly.

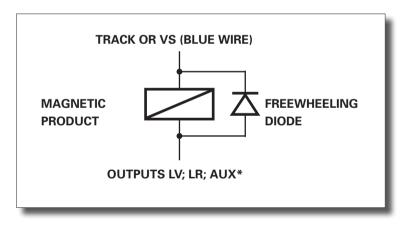


### Supplement 4: Electric coupling / Freewheeling diode

Electric couplings – i.e. couplings, which can automatically uncouple remotely — are magnetic articles and therefore inductive consumers.

When switiching off the current they may generate by the coil of the magnetic product a high voltage with opposite polarity (up to several hundred volts) by self induction. By exceeding the maximum cut off voltage of the function outputs of the most sensitive MOSFET output drivers, they can be destroyed irreparably!

#### It is therefore imperative to close shortly these voltages by freewheeling diodes:



Please make sure that the function output you have chosen for connecting the electric coupling has a sufficiently high capacity! We recommend the connections AUX3 and AUX4 of our decoders, which are designed for currents up to 1 A.

#### Hint:

Use the coupling functions of our decoders (timer for switching off AUX\*) to make sure that the function output will be switched off in any case according to a maximum activation time specified by you. Otherwise the destruction of the electric coupling is possible.

Refer to automatic coupling prcedure.

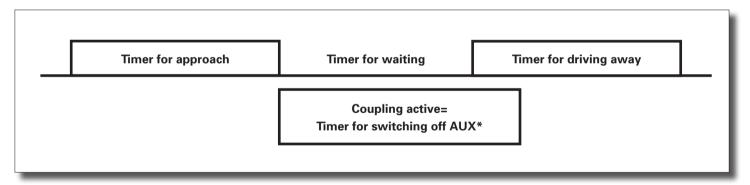


# Automatic coupling procedure ("coupling waltz") Principle function

If a locomotive with attached wagon train has been driven into the station in forward driving and now the wagon train should be uncoupled, the locomotive must approach the wagon train backwards to relieve the coupling. Then the coupling must be activated by relaxed towing hook. Now the locomotive is driving away with activated coupling a bit, until the coupling is in rest position.

"Coupling waltz" is not assigned to a function; it is automatically available, as long as it is activated by CV143 Bit 6 = 0.

The time procedure is defined by CVs (see chart):



CV138 Timer for approach

CV139 Timer for waiting

CV140 Timer for driving away

Using the coupling function of our decoder it must be ensured that the function output will be switched off in any case according to a maximum activation time specified by you. Otherwise the destruction of the electric coupling is possible.

The time, while coupling is activated, is defined by the switching off function:

CV117 Timer for switching off AUX1

CV118 Timer for switching off AUX2

CV119 Timer for switching off AUX3

CV120 Timer for switching off AUX4

CV129 Timer for switching off AUX5

CV130 Timer for switching off AUX6

#### Please proceed as follows:

For function output AUX1 please use CV 117 (par076)

For function output AUX2 please use CV 118 (par077)

For function output AUX3 please use CV 119 (par078)

For function output AUX4 please use CV 120 (par079)

For function output AUX5 please use CV 129 (par145)

For function output AUX6 please use CV 130 (par146)

The adjusted value is internal multiplied by 100 milliseconds. If you want for example to achieve a maximum activation time of one second, please program the value 10.

Value 0 means no coupling function.

That a coupling waltz should be executed the decoder recognizes by the fact that a value unevenly 0 is entered at different times.



#### Operating the couplings with 2 function keys

Should the couplings be connected for example to AUX3 (in front) and AUX4 (at the rear), times are to be entered at AUX3 and AUX4. The mapping of the function keys (which function key should control which coupling), is set by the normale function mapping (see next page).

For example F3 = AUX3 and F4 = AUX4 should be assigned:

CV37 Function mapping F3 (in the example = 16 for AUX3)

CV38 Function mapping F4 (in the example = 32 for AUX4)

#### Operating the couplings with 1 function key

Should the couplings be connected for example to AUX3 (in front) and AUX4 (at the rear), times are to be entered at AUX3 and AUX4. The corresponding function key must now be assigned to both couplings.

For example shall F4 = AUX3 and AUX4 operate:

CV38 Function mapping F4 (in example = 16 + 32 = 48 for AUX3 + AUX4)

Which coupling should react must be defined by a condition.

In the example AUX3 should that be for forward and AUX4 for backward:

CV149 Condition for AUX3: forward only = 1

CV150 Condition for AUX4: backward only = 2

# **Supplement 5: Constant braking distance** Function of the "braking ramp"

Set the desired braking method in CV27 / par91. Set in CV48 / par051 the linear characteristic (value = 0).

Make sure that CV154 / par096 contains the value 0. Before proceeding, please check if the model reaches a reasonable top speed with the highest speed step. If it is slower, please increase the value in CV05 / par013. If it is faster, please reduce the value in CV05 / par013.

Note the current value from CV04 / par012. Let the model enter the braking section with the highest speed step. If the model stops too early, please increase the value in CV04 / par012. If the model stops too late (drives through), please reduce the value in CV04 / par012. Repeat the entry into the braking section until the most suitable value for CV04 / par012 is found.

Now set the determined value for CV04 / par012 multiplied by 8 in CV154 / par096. If you want a fine tuning, you can vary the value in CV154 / par096 in the range of -7 to  $\pm$ 7. Reset CV04 / par012 to the noted value.

The decoder now automatically calculates the necessary "braking ramp" for all other speed steps when entering the braking section.

For pushed reversing trains etc. a separate value for reverse direction is available with CV155 / par097. If CV155 / par097 contains the value "0", CV154 / par096 is valid for both driving directions. If CV155 / par097 contains a value higher than "0", CV154 / par096 is only valid for forward direction.



# Supplement 6: Decoder detection Which decoder is it?

Please read out the CV261. You can determine the decoder by the read out value with the help of the listing of the CV261 in the CV table of this description.

#### How do I recognize the firmware version of the decoder?

Please read out the CV264. The read out value must be at least as big as the value after the dot in the above firmware version bar next to our logo.

If this should not be the case, an older description is required for your decoder.

## **Supplement 7: Speed feedback**

The decoders are able to report their current speed in km/h to the digital system by means of bidirectional communication (RailCom®). For this purpose, it is necessary to enter the measured model speed at the highest speed step in km/h (determined, for example, by measuring cars, the time span between two track points of known distance, etc.) into CV135 and CV136.

The formula for this is: Speed = 
$$\frac{\text{speed step} \times \text{CV135}}{2^{\text{CV136}}}$$

Here are some exemplary values:



km/h	CV135	CV136
none	0	no matter
5	3	6
10	5	6
15	8	6
20	10	6
25	13	6
30	15	6
35	18	6
40	20	6
45	23	6
50	25	6
60	30	6
70	35	6
80	40	6
90	45	6

km/h	CV135	CV136
100	50	6
110	55	6
120	60	6
130	66	6
140	71	6
160	81	6
150	76	6
170	86	6
180	91	6
190	96	6
200	101	6
210	106	6
220	111	6
230	116	6
240	121	6



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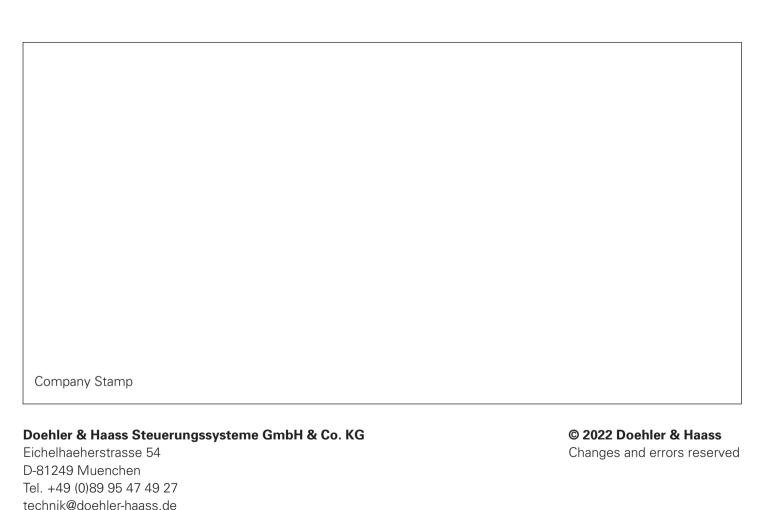


Achtung: Nicht für Kinder unter 36 Monaten geeignet wegen verschluckbarer Kleinteile, Erstickungsgefahr.

Caution: Not suitable for children under 36 months due to small parts which may be swallowed, choking hazard.

Attention : ne convient pas aux enfants de moins de 36 mois en raison de petites pièces pouvant être avalées, risque d'étouffement.





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